

**Project 1 Documentation Report**

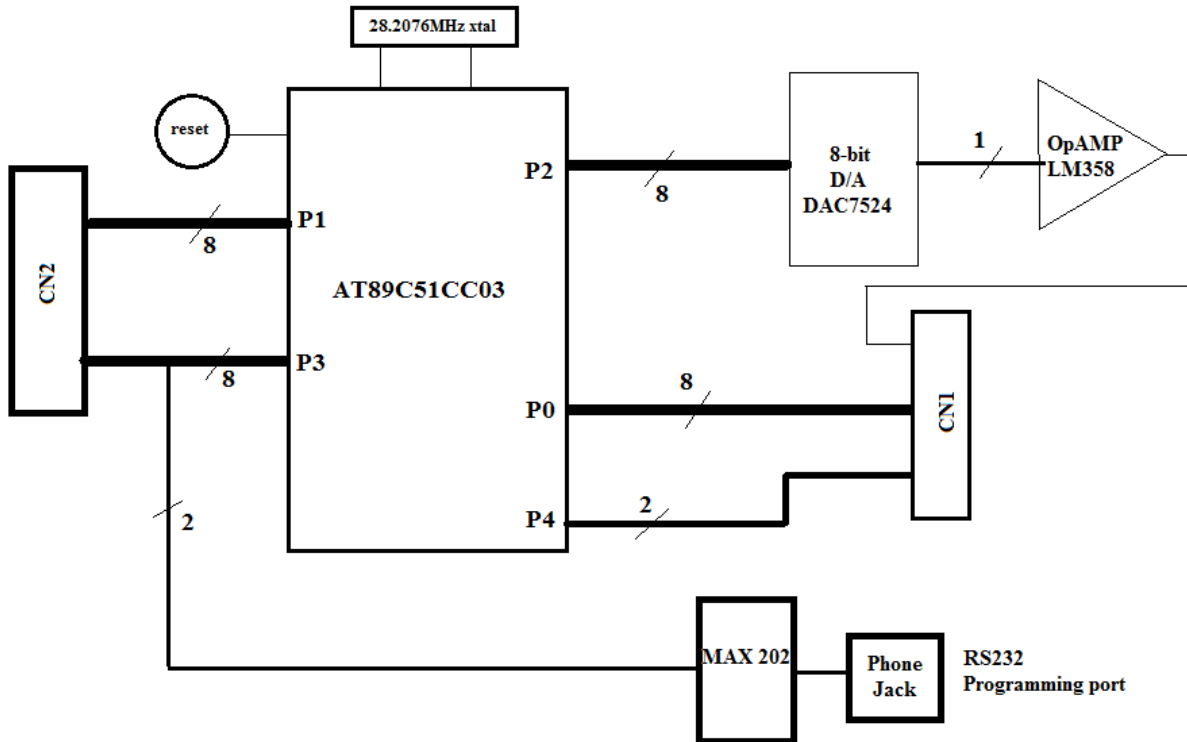
The project report should consist of:

- A cover sheet with your name, the project number and title, and the date turned in.
- A list of novel features. Creativity may consist of novel hardware or software implemented features or a novel packaging technique.
- A list of those items you were able to demonstrate as working to the instructor.
- A discussion of how you considered safety, reliability, economic, manufacturability, and environmental factors. You need a few sentences describing what you did for each area.
- An estimate based on theoretical and empirical data as to the power requirements.
- Hardware documentation. At a minimum your hardware documentation must consist of a system diagram, a complete circuit diagram (with pin numbers), and a mechanical sketch or photo of your project done to a level of detail such that another person in the class could build your project from your diagram.
- Software documentation. At a minimum your software documentation should consist of fully commented source code for all of the modules in your program and a pseudocode design with enough detail that another person in the class could duplicate the function of your software. Your pseudocode must match your actual C-code.

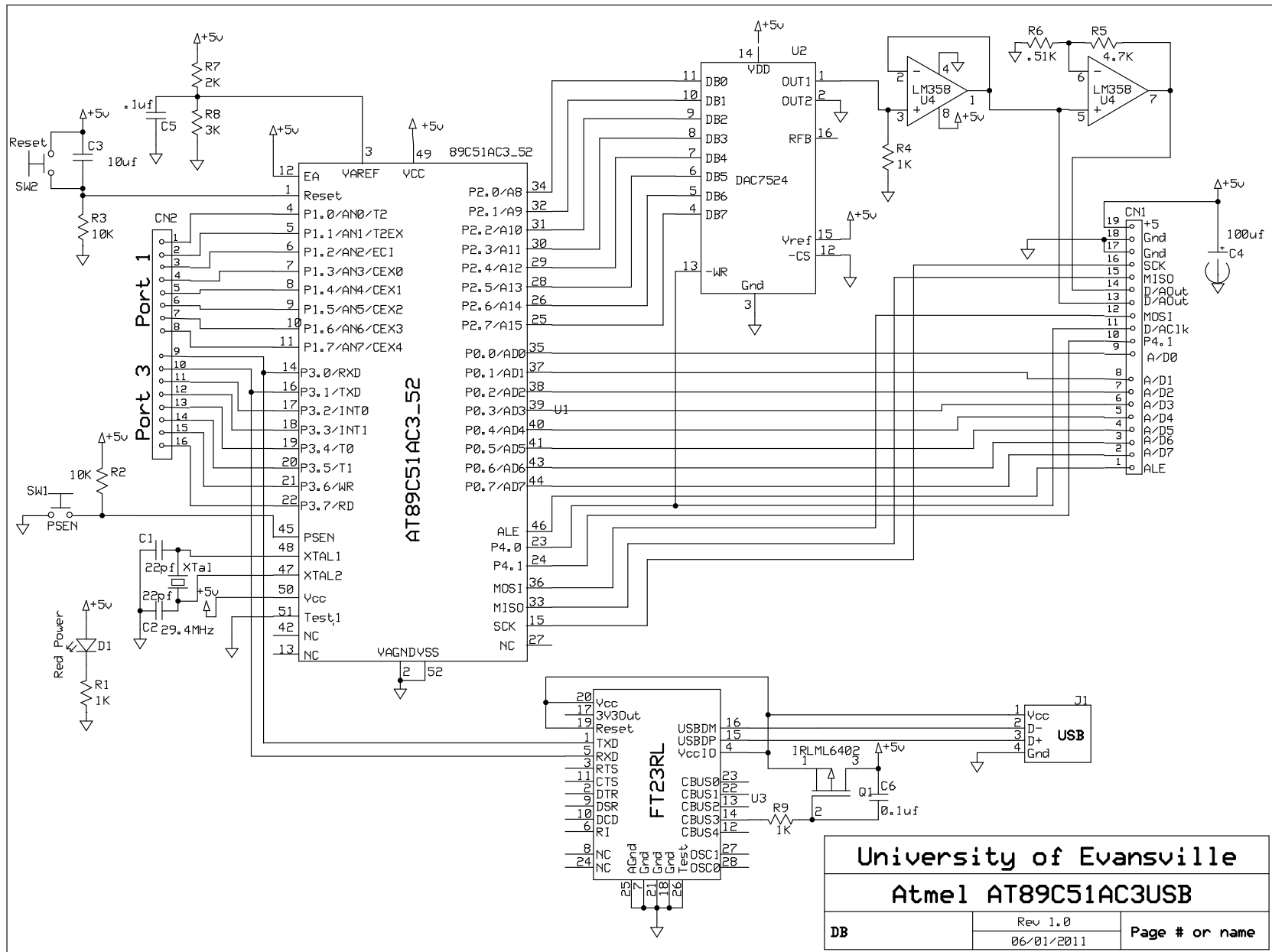
# EE 354

## Hardware Diagram Samples

Sample 1: System Diagram for the AT89C51CC03 board



Sample 2: Circuit Diagram for the AT89C51CC03 Board.



## EE 354 Pseudo Code Sample

Initialize global interrupt variables for timer 0 multiplexing

Initialize global constants

```
code unsigned char LEFT = xxx;
```

Initialize global variables

```
unsigned char refreshRow = 0; //row to be refreshed
```

```
unsigned char LED[16]; //Memory map of LED matrix
```

Main code

```
{Initialize timer 0 interrupt
```

```
Set up timer 0 for multiplexing
```

```
Set up timer 1 for ball speed
```

```
Set up A/D converter for paddles
```

```
Initialize variables
```

```
Clear LED memory map
```

```
Place paddles in memory map
```

```
unsigned char ballDir //0 = left 1 = right
```

```
unsigned char ballRow, ballCol
```

```
Start timer for multiplexing display
```

```
while(game is not over) //main program loop
```

```
{Wait for game serve switch
```

```
Start ball speed timer (timer 1)
```

```
ballRow = 3;ballCol = 0;
```

```
ballDir = 0 //left
```

```
while(turn continues)
```

```
{MoveBall(ballRow, ballCol, ballDir)
```

```
if(ball is at paddle)
```

```
{if ball misses paddle
```

```
{turn is over
```

```
update score
```

```
if(score at end)
```

```
announce winner
```

```
game over
```

```
}
```

```
else
```

```
ballDir = ~ballDir
```

```
}
```

```
Check and set left paddle
```

```
Check and set right paddle
```

```
wait for ball speed timer to run out
```

```
}
```

```
}
```

```
}
```

```
while(1); Game is over wait for reset
```

Timer 0 multiplexor interrupt

```
{reload the timer value
```

```
Get the data d = LED[refreshRow]
```

```
Convert refreshRow to port bits for decoders
```

```
Make decoders active
```

```
Send d to the 74LS244 port
```

```
Update refreshRow
```

```
}
```

Notes:

1. In this version the player always plays against the computer. The player always serves.
2. The ball only goes back and forth – not up or down. To get the ball to go up a row or down a row when it is hit you need to keep track of where on the paddle the ball was hit and move the ball up or down when it reaches the middle of the array.